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Corporate Social Responsibility, Environmental Emissions and Time-Consistent Taxation

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Motiva	ition				

- There is an increase in the adoption of voluntary corporate practices by firms that pay attention to consumer welfare, environmental issues, and green production.
- KPMG Survey of Sustainability Reporting 2020:
 - 80% of companies worldwide report on sustainability.
 - 40% of companies acknowledge the financial risks of climate change.
 - Most firms have targets in place to reduce their carbon emissions.
- ESG criteria are a set of standards designed to enhance transparency and accountability within a firm's operations, guiding them towards improved governance, environmental-friendly practices, and social responsibility (United Nations, 2004; 2023).

Motivation: Voluntary corporate decisions adopted by part of the automotive industry

- In 2019, Volvo confirmed the end of its diesel engines in favor of electrification and hybrid solutions to lower emissions.
- In 2020, BMW committed to procuring 100% of its electricity from renewable sources for its operations by 2050.
- Mercedes-Benz is also committed to making its entire passenger car fleet carbon-neutral by the close of 2039.
- In 2019, Volkswagen accelerated plans to electrify its fleet, committing to launch 70 fully electric models by 2028.
- Tesla has become the most valuable automaker by market cap.

See for instance:

Motivation

www.carthrottle.com/post/volvo-has-finally-confirmed-the-end-of-its-diesel-engines

www.wemeanbusinesscoalition.org/blog/

bmw-joins-growing-list-of-automakers-committed-to-boldclimate-action/

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Quest	ions addres	ssed						

- O How optimal emission taxation must address CSR motivations?
- What CSR motivations are better for reducing environmental emissions?

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Proble	m						

- We formally model a Cournot duopoly market in which a corporate socially responsible (CSR) firm interacts with a profit-maximizing firm and where the market is regulated with an emission tax.
- We consider three different kinds of CSR firm behaviors:
 - consumer-friendly.
 - ii environmentally-friendly.
 - iii consumer-environmentally friendly.
- To the best of our knowledge, this work is the first to formally solve a Cournot duopoly analyzing different types of CSR behavior under a time-consistent emission tax.

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Relate	d Literature	e						

- Pigouvian taxation: attempt to internalize marginal environmental damage through taxation.
 - Perfect competition: Pigou, 1920. The Economics of Welfare & Baumol, 1972. On taxation and the control of externalities.
 - Monopoly: Barnett, 1980. The Pigouvian tax rule under monopoly.
 - Oligopoly: Simpson, 1995. Optimal pollution taxation in a Cournot duopoly.
- Time-consistent game: Petrakis & Xepapadeas, 2003. Location decisions of a polluting firm and the time consistency of environmental policy.

Related Literature: CSR-firms as consumer-friendly firms

Authors	Title	Year	CSR-firm's objective function
Kim, SL, Lee, SH, & Mat- sumura, T	Corporate social respon- sibility and privatiza- tion policy in a mixed oligopoly	2019	$U_i = \pi_i + \alpha CS$, where $\alpha_i \in (0, 1)$ represents the CSR level, which is exogenously given. That is, CSR implies the private firm is interested in consumers' surplus in addition to its profit.
García, A, Leal, M & Lee, SH	Time-inconsistent envi- ronmental policies with a consumer-friendly firm: Tradable permits versus emission tax	2018	$V_0 = \pi_0 + \theta CS$, where $\theta \in [0, 1]$ measures the degree of concern on consumer surplus that the consumer- friendly firm has, which is exogenously given.
Xu, L & Lee, SH	Corporate Social Re- sponsibility and Envi- ronmental Taxation with Endogenous Entry	2018	$G = \pi_0 + \alpha CS$, where $\alpha \in [0, 1]$. They assume that CSR initiative includes both profitability and consumer surplus, as a proxy of its concern for consumers, and thus the objective of the CSR-firm is a combination of consumer surplus and its profit.
Fanti, L & Buccella, D	Corporate social re- sponsibility, profits and welfare with managerial firms	2017	$W_i = \pi_i + kCS$, where $k \in [0, 1]$ denotes the weight that CSR firms assign to consumer surplus.

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Authors	Title	Year	CSR-firm's objective function
Lambertini, L & Tampieri, A	Incentives, performance and desirability of so- cially responsible firms in a Cournot oligopoly	2015	$O_c sr = \pi_{csr} - gq_{csr} + zQ^2/2$, where O_{csr} represents the objective function of a firm adopting a CSR statute, gq_{csr} represents environmental damage and $z \in [0, 1]$ denotes the weight that the firm assigns to consumer surplus.
Matsumura, T & Ogawa, A	Corporate Social Re- sponsibility or Payoff Asymmetry? A Study of an Endogenous Timing Game	2014	$V_i = \theta_i SW + (1 - \theta_i)\pi_i$, where $\theta_i \in [0, 1)$, SW is the total social surplus (sum of the firms' profits and consumer surplus), and π_i is firm i's profit.
Goering, G	The Profit-Maximizing Case for Corporate So- cial Responsibility in a Bilateral Monopoly	2014	$\lambda_r = \pi_r + \gamma CS$, where π_r represents profits plus a given fraction ($\gamma > 0$) of the consumer surplus (CS) of its customers'.
Brand, B & Grothe, M	Social responsibility in a bilateral monopoly	2014	$\nu_i = \pi_i + \theta_i CS$, where θ_i indicates the weight put on consumer surplus.

Related Literature: CSR-firms as environment-friendly firms

Literature Review

Authors	Title	Year	CSR-firm's objective function
Barcena- Ruiz, JC & Sagasta, A	International trade and environmental corporate social responsibility	2022	$V_i = \pi_i - \alpha ED_i$, where ED_i is the cost of factoring environmental considera- tions into all business activities, with $\alpha \in [0, 1/2]$ is the weight attached to environmental damage.
Xu, L; Chen, Y & Lee, SH	Emission tax and strate- gic environmental corpo- rate social responsibil- ity in a Cournot–Bertrand comparison	2022	$V_i = \pi_i + \beta ED$, where $\beta_i \in [0, 1]$ is the degree of ECSR (environmental corporate social responsibility).
Fukuda K & Ouchidab Y	Corporate social respon- sibility (CSR) and the en- vironment: Does CSR in- crease emissions?	2022	$V = \pi + \theta(CS - D(E))$, where $\theta \in [0, 1]$ is the degree of CSR. $\theta(CS - D(E))$ is called social concern.

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The m	odel						

- Consider an industry with two polluters: one CSR firm and a profit-maximizing private firm, which competes à la Cournot.
- Total output: $Q = q_0 + q_1$.
- Inverse demand function f(Q).
- Both firms discharge pollution into the environment, d_i, generating D(d₀, d₁) in total environmental damage.
- Total productions costs: c_i = c(q_i, w_i), where w_i represents resources devoted to pollution treatment.
- Two ways of reducing *d_i*: reduce output *q_i*, or more resources *w_i* to the abatement of pollution.
- We also consider a tax on emissions, *t*, which is chosen by the regulator.

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The m	odel						

Firms profit function:

$$\pi_i(\boldsymbol{q}_i, \boldsymbol{w}_i) = f(\boldsymbol{Q})\boldsymbol{q}_i - \boldsymbol{c}(\boldsymbol{q}_i, \boldsymbol{w}_i) - \boldsymbol{d}_i(\boldsymbol{q}_i, \boldsymbol{w}_i)t \tag{1}$$

In addition, the CSR firm cares not only for its profits but also for a fraction of the consumer surplus, *CS*, as a proxy of the firm's concern for consumers and/or for environmental damage produced by the duopoly, *D*, as a proxy of the firm's concern for the environment:

$$\nu_0 = \pi_0 + \theta CS - \gamma D(d_0, d_1)$$
⁽²⁾

The interest of the regulator is the social welfare:

$$SW = CS + f(Q)(q_0 + q_1) - c_0 - c_1 - D(d(q_0, w_0), d(q_1, w_1))$$
(3)

with $CS = \int_0^Q f(z) dz - f(Q) Q$

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Some	definitions						

- Profit Maximizing Firm (pm): The firm has only a profit maximizing objective ⇒ θ = 0 and γ = 0.
- Consumer friendly Firm (cf): Its objective is a combination of consumer surplus, and its profit ⇒ θ > 0 and γ = 0.
- Environmentally friendly Firm (ef): Maximize its material profit minus environmental emissions produced by the duopoly $\Rightarrow \theta = 0$ and $\gamma > 0$.
- Consumer-Environment friendly Firm (cef): Its objective is a combination of consumer surplus, and its profit minus environmental emissions produced by the duopoly ⇒ θ > 0 and γ > 0.

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Assum	nptions						

- The inverse demand function *f*(*Q*) is twice continuously differentiable, with ^{∂f(Q)}/_{∂Q} < 0 whenever *f*(*Q*) > 0 and lim_{Q→∞} *f*(*Q*) = 0, with *q*₀, *q*₁ ≥ 0.
- Cost functions c = c(q_i, w_i) ∀i = 0, 1 are increasing and twice continuously differentiable.
- The emission level functions $d = d(q_i, w_i)$ and the emissions damage function $D(d(q_0, w_0), d(q_1, w_1)) \forall i = 0, 1$ are increasing in production, $\frac{\partial d}{\partial q_i} > 0$ and $\frac{\partial D}{\partial q_i} > 0$ and decreasing in abatement effort, $\frac{\partial d}{\partial w_i} < 0$ and $\frac{\partial D}{\partial w_i} < 0$, and twice continuously differentiable, with $\frac{\partial^2 D}{\partial q_i^2} > 0$ and $\frac{\partial^2 D}{\partial w_i^2} > 0$.



The optimization problem faced by the private firm:

$$\max_{q_1,w_1} \pi_1(q_1,w_1) = f(Q)q_1 - c_1(q_1,w_1) - d_1(q_1,w_1)t$$
(4)

The optimization problem faced by the CSR firm:

$$\max_{q_0, w_0} \nu_0(q_0, w_0) = f(Q)q_0 - c_0(q_0, w_0) - d_0(q_0, w_0)t + \\ \theta\left(\int_0^Q f(z)dz - f(Q)(Q)\right) - \gamma D(d_0(q_0, w_0), d_1(q_1, w_1))$$
(5)

The optimization problem faced by the regulator:

$$\max_{t} SW = \int_{0}^{Q} f(z) dz - c_{0}(q_{0}, w_{0}) - c_{1}(q_{1}, w_{1}) - D(d_{0}(q_{0}, w_{0}), d_{1}(q_{1}, w_{1}))$$
(6)

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 The model:
 Two strategies to solve the problem

- Simultaneous game (Barnett, 1980).
- Three-stage sequential game (Petrakis & Xepapadeas, 2003).

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Simultaneous game (Barnett, 1980).

O Three-stage sequential game (Petrakis & Xepapadeas, 2003).

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Definition

A strategy for the regulator is a tax amount $t \ge 0$ and a strategy for the firms is $\rho_i(q_i, w_i)$, where $\rho_i(\cdot)$ is a mapping of the decisions (q_i, w_i) . An equilibrium of this simultaneous game is a triplet $(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*))$ such that:

- (i) $\pi_1(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*)) \ge \pi_1(t^*, \rho(q_0^*, w_0^*), \rho(q_1, w_1^*))$
- (ii) $\pi_1(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*)) \ge \pi_1(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1))$
- (iii) $\nu_0(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*)) \ge \nu_0(t^*, \rho(q_0, w_0^*), \rho(q_1^*, w_1^*))$
- (iv) $\nu_0(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*)) \ge \nu_0(t^*, \rho(q_0^*, w_0), \rho(q_1^*, w_1^*))$
- (v) $SW(t^*, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*)) \ge SW(t, \rho(q_0^*, w_0^*), \rho(q_1^*, w_1^*))$

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Some	results							

The welfare maximizing tax is given by:

$$t_{sim}^{*} = \frac{(1-\gamma)\frac{\partial D}{\partial d_{0}}\frac{\partial d_{0}^{*}}{\partial t} + \frac{\partial D}{\partial d_{1}}\frac{\partial d_{1}^{*}}{\partial t}}{\frac{\partial d_{0}^{*}}{\partial t} + \frac{\partial d_{1}^{*}}{\partial t}} + \frac{(q_{0} - \theta Q)\frac{dq_{0}^{*}}{dt}\frac{\partial f(Q)}{\partial q_{0}} + q_{1}\frac{dq_{1}^{*}}{dt}\frac{\partial f(Q)}{\partial q_{1}}}{\frac{\partial dq_{0}^{*}}{\partial t} + \frac{\partial d_{1}^{*}}{\partial t}}$$
(7)

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Corollary

An increase in parameter θ , which represents the fraction of total consumer surplus that is of concern to the CSR firm, increases the equilibrium

Pigouvian tax: $\frac{dt_{sim}^*}{d\theta} = -\frac{Q^* \frac{dq_0^*}{dt} \frac{\partial t(Q^*)}{\partial q_0}}{\frac{\partial dq_0^*}{\partial t} + \frac{\partial dq_0^*}{\partial t}} > 0$, while an increase in parameter γ , which measures the CSR firm's degree of concern on environmental emissions, decreases the equilibrium Pigouvian tax:

$$\frac{dt_{sim}^*}{d\gamma} = -\frac{\frac{\partial D}{\partial d_0} \frac{\partial \sigma_0}{\partial t}}{\left(\frac{\partial d_0^*}{\partial t} + \frac{\partial d_1^*}{\partial t}\right)} < 0.$$

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Proposition

In the duopoly setting in which a CSR firm interacts with a profit-maximizing firm, tax comparison for different CSR motivations is as follows:

(i)
$$t_{ef}^* \leq t_{pm}^* \leq t_{cf}^*$$

(ii) $t_{ef}^* \leq t_{pm}^* < t_{cef}^* \leq t_{cf}^*$ whenever $\theta Q \frac{\partial f(Q)}{\partial q_0} \frac{dq_0^*}{dt} + \gamma \frac{\partial D}{\partial d_0} \frac{\partial d_0^*}{\partial t} > 0$
(iii) $t_{ef}^* \leq t_{cef}^* \leq t_{pm}^* \leq t_{cf}^*$ whenever $\theta Q \frac{\partial f(Q)}{\partial q_0} \frac{dq_0^*}{dt} + \gamma \frac{\partial D}{\partial d_0} \frac{\partial d_0^*}{\partial t} \leq 0$



Graphically

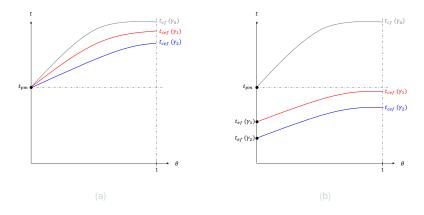


Figure: Optimal Pigouvian Taxes for different CSR motivations $(\gamma_0 = 0 < \gamma_1 < \gamma_2)$

- Panel (a) shows condition (ii) form Proposition.
- Panel (b) shows condition (iii) from Proposition.

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Simultaneous game (Barnett, 1980).

Three-stage sequential game (Petrakis & Xepapadeas, 2003).

The three-stage sequential game

- Time consistent game. Why?
 - Decisions that involve investment Abatement \Rightarrow sunk cost.
 - It is not credible that the regulator will announce its tax policy before knowing the committed abatement investment by the firms.
- Therefore, we model the problem in a three-stage game and we restrict our attention to pure strategies.
 - First stage: the firms decide simultaneously their abatement effort w_i.
 - Second stage: the regulator imposes the tax t.
 - Third stage: the firms decide simultaneously their production level *q*_i.

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Definition

A strategy for the regulator is a tax amount $t \ge 0$ and a strategy for the firms is $\rho_i(q_i, w_i)$, where $\rho_i(\cdot)$ is a mapping of the decisions (q_i, w_i) .

The firms are the first movers with their abatement decision, where an equilibrium is given by:

- (i) $\pi_1(\rho_1(q_1^*, w_1^*)) \ge \pi_1(\rho_1(q_1^*, w_1))$
- (ii) $\nu_0(\rho_0(q_0^*, w_0^*)) \ge \nu_0(\rho_0(q_0^*, w_0))$

The regulator is a second-mover player, and the equilibrium is such that:

(i)
$$SW(t^*, \rho_i(\boldsymbol{q}_i^*, \boldsymbol{w}_i)) \geq SW(t, \rho_i(\boldsymbol{q}_i^*, \boldsymbol{w}_i))$$

The firms are the third mover with the production decision, where an equilibrium is:

(i)
$$\pi_1(\rho_1(q_1^*, w_1)) \ge \pi_1(\rho_1(q_1, w_1))$$

(ii) $\nu_0(\rho_0(q_0^*, w_0)) \ge \nu_0(\rho_0(q_0, w_0))$

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The SPNE welfare-maximizing tax for the three-stage sequential game is:

$$t_{3stage}^{*} = \frac{\frac{\partial q_{1}}{\partial w_{1}} \left(\frac{\partial c_{0}}{\partial w_{0}} + d_{0} \frac{\partial t}{\partial w_{0}} + \theta Q \frac{\partial t(Q)}{\partial w_{0}} + \gamma \frac{\partial D}{\partial w_{0}} - q_{0} \frac{\partial f(Q)}{\partial w_{0}} \right)}{\frac{\partial q_{0}}{\partial w_{0}} \frac{\partial d_{1}}{\partial w_{1}} - \frac{\partial q_{1}}{\partial w_{1}} \frac{\partial d_{0}}{\partial w_{0}}}{\frac{\partial q_{0}}{\partial w_{0}} \left(\frac{\partial c_{1}}{\partial w_{1}} + d_{1} \frac{\partial t}{\partial w_{1}} - q_{1} \frac{\partial f(Q)}{\partial w_{1}} \right)}{\frac{\partial q_{0}}{\partial w_{0}} \frac{\partial d_{1}}{\partial w_{1}} - \frac{\partial q_{1}}{\partial w_{0}} \frac{\partial d_{0}}{\partial w_{0}}}$$
(8)

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Corollary

 $\begin{array}{l} \label{eq:Whenever} & \frac{\frac{\partial q_1}{\partial w_1}}{\frac{\partial q_0}{\partial w_0} \frac{\partial d_1}{\partial w_1} - \frac{\partial q_1}{\partial w_0}} > 0, \mbox{ an increase in the fraction of consumer} \\ \mbox{ surplus that is concern to the CSR firm, } \theta, \mbox{ will increase the equilibrium} \\ \mbox{Pigouvian tax, that is } \frac{\partial t^*_{3stage}}{\partial \theta} = \frac{\mathcal{Q} \frac{\partial q_1}{\partial w_1} \frac{\partial (\mathcal{Q})}{\partial w_0}}{\frac{\partial q_0}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial (\mathcal{Q})}{\partial w_0}} > 0 \ \mbox{only when } \frac{\partial f(\mathcal{Q})}{\partial w_0} > 0. \ \mbox{On the other hand, an increase in parameter } \gamma, \ \mbox{ the degree of concern on environmental emissions, decreases the equilibrium Pigouvian tax, which} \\ \mbox{means } \frac{\partial t^*_{3stage}}{\partial \gamma} = \frac{\frac{\partial q_1}{\partial w_1} \frac{\partial D}{\partial w_0}}{\frac{\partial q_1}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial q_0}{\partial w_0}} < 0. \end{array}$

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Proposition

Whenever $\frac{\partial q_1}{\partial w_1} > 0$, $\frac{\partial f(Q)}{\partial w_0} > 0$ and $\frac{\partial q_0}{\partial w_0} \frac{\partial d_1}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial d_0}{\partial w_0} > 0$, in the three-stage ex-post game in which a CSR firm interacts with a profit-maximizing firm, taxes comparison for different CSR motivations is as follows:

(i)
$$t_{ef}^* \leq t_{pm}^* \leq t_{cf}^*$$

(ii) $t_{ef}^* \leq t_{pm}^* \leq t_{cef}^* \leq t_{cf}^*$ whenever $\theta Q \frac{\partial f(Q)}{\partial w_0} + \gamma \frac{\partial D}{\partial w_0} > 0$
(iii) $t_{ef}^* \leq t_{cef}^* \leq t_{pm}^* \leq t_{cf}^*$ whenever $\theta Q \frac{\partial f(Q)}{\partial w_0} + \gamma \frac{\partial D}{\partial w_0} < 0$



Graphically

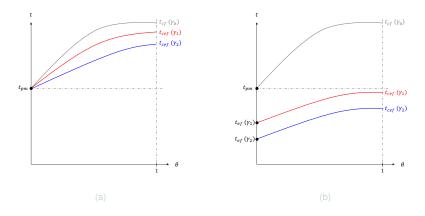


Figure: Optimal Pigouvian Taxes for different CSR motivations $(\gamma_0 = 0 < \gamma_1 < \gamma_2)$

- Panel (a) shows condition (ii) form Proposition.
- Panel (b) shows condition (iii) from Proposition.

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Policy	implication	IS					

- Strategic behavior.
- Price elasticity of demand.

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Definition (Bulow et al., 1985)

After totally differentiating the first-order conditions, we have that:

- **Substitutes** implies that $\frac{\partial \pi_1}{\partial q_0} < 0 \left(\frac{\partial \nu_0}{\partial q_1} < 0 \right)$, that is, firm's 1 (firm's 0) profitability is less when firm 0 (firm 1) increases its output, q_1 (q_0), (or acts more aggressively). *Strategic substitutes* in turn are defined as $\frac{\partial^2 \pi_1}{\partial q_1 \partial q_0} < 0 \left(\frac{\partial^2 \nu_0}{\partial q_0 \partial q_1} < 0 \right)$, meaning that the marginal profit of firm 1 is less when firm 0 acts more aggressively.
- **Complements** implies that $\frac{\partial \pi_1}{\partial q_0} > 0$ ($\frac{\partial \nu_0}{\partial q_1} > 0$), that is, firm's 1 (firm's 0) profitability is more when firm 0 (firm 1) increases its output, q_1 (q_0), (or acts more aggressively). *Strategic complements* in turn are defined as $\frac{\partial^2 \pi_1}{\partial q_1 \partial q_0} > 0$ ($\frac{\partial^2 \nu_0}{\partial q_0 \partial q_1} > 0$), meaning that the marginal profit of firm 1 is more when firm 0 acts more aggressively.

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Solving we know that:

$$q_1 = \frac{\frac{\partial c_1}{\partial q_1} + t \frac{\partial d_1}{\partial q_1} - f(Q)}{\frac{\partial f(Q)}{\partial q_1}} \text{ and } q_0 = \frac{\frac{\partial c_0}{\partial q_0} + t \frac{\partial d_0}{\partial q_0} + \gamma \frac{\partial D}{\partial d_0} - f(Q)}{(1-\theta) \frac{\partial f(Q)}{\partial q_0}} + \frac{\theta}{1-\theta} q_1.$$

 Comparing the reaction functions of firm 0 when θ = 0 and γ = 0 versus θ > 0 and γ > 0, it is clear that the firm's output in the first case is higher than in the second case:

$$\frac{\frac{\partial c_0}{\partial q_0} + t \frac{\partial d_0}{\partial q_0} - f(\mathcal{Q})}{\frac{\partial f(\mathcal{Q})}{\partial q_0}} \geq \frac{\frac{\partial c_0}{\partial q_0} + t \frac{\partial d_0}{\partial q_0} + \gamma \frac{\partial D}{\partial q_0} - f(\mathcal{Q})}{(1 - \theta) \frac{\partial f(\mathcal{Q})}{\partial q_0}} + \frac{\theta}{1 - \theta} q_1.$$

• The response of firm 1 to the behavior of firm 0 is to increase its

production:
$$\frac{\partial q_1}{\partial q_0} = -\frac{\frac{\partial f(Q)}{\partial q_0} + q_1 \frac{\partial^2 f(Q)}{\partial q_0 \partial q_1}}{\frac{\partial f(Q)}{\partial q_1}} < 0.$$

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Using:
$$\eta_{i} = -\frac{f(Q^{*})}{q_{i}^{*}} \frac{\partial q_{i}^{*}}{\partial t(Q^{*})},$$

$$\frac{\partial f(Q)}{\partial w_{i}} = \frac{\partial f(Q)}{\partial q_{i}} \frac{\partial q_{i}}{\partial w_{i}} \text{ and } \frac{\partial D}{\partial w_{i}} = \frac{\partial D}{\partial d_{i}} \frac{\partial d_{i}}{\partial w_{i}}, \forall i = 0, 1, \text{ we can re-write } t^{*} \text{ as:}$$

$$t_{sim}^{*} = \frac{(1-\gamma)}{\frac{\partial D}{\partial d_{0}}} \frac{\partial d_{0}^{*}}{\partial t} + \frac{\partial D}{\partial d_{1}} \frac{\partial d_{1}^{*}}{\partial t} - \frac{\frac{f(Q^{*})}{\eta_{0}} \frac{d q_{0}^{*}}{dt} + \frac{f(Q^{*})}{\eta_{1}} \frac{d q_{1}^{*}}{dt} + \theta Q \frac{d q_{0}^{*}}{dt} \frac{\partial f(Q)}{\partial q_{0}}}{\frac{\partial d q_{0}^{*}}{\partial t} + \frac{\partial d_{1}^{*}}{\partial t}} - \frac{\frac{f(Q^{*})}{\eta_{0}} \frac{d q_{0}^{*}}{dt} + \frac{f(Q^{*})}{\eta_{1}} \frac{d q_{1}^{*}}{dt} + \theta Q \frac{d q_{0}^{*}}{dt} \frac{\partial f(Q)}{\partial q_{0}}}{\frac{\partial d q_{0}^{*}}{\partial t} + \frac{\partial d_{1}^{*}}{\partial t}} \qquad (9)$$

$$t_{3stage}^{*} = \frac{\frac{\partial q_{1}}{\partial w_{1}} \left(\frac{\partial c_{0}}{\partial w_{0}} + d_{0} \frac{\partial t}{\partial w_{0}} + (1-\theta) \frac{f(Q)}{\eta_{0}} \frac{\partial q_{0}}{\partial w_{0}} + \gamma \frac{\partial D}{\partial d_{0}} \frac{\partial d_{0}}{\partial w_{0}}}{\frac{\partial q_{0}}{\partial w_{0}} - \frac{\partial q_{1}}{\partial w_{1}} - \frac{\partial q_{1}}{\partial w_{1}} \frac{\partial q_{0}}{\partial w_{0}}}{\frac{\partial q_{0}}{\partial w_{0}} \frac{\partial d_{1}}{\partial w_{1}} - \frac{\partial q_{1}}{\partial w_{1}} \frac{\partial q_{0}}{\partial w_{0}}}{\frac{\partial q_{0}}{\partial w_{0}} - \frac{\partial q_{1}}{\partial w_{0}} \frac{\partial q_{0}}{\partial w_{0}}}{\frac{\partial q_{0}}{\partial w_{0}} \frac{\partial d_{1}}{\partial w_{1}} - \frac{\partial q_{1}}{\partial q_{1}} \frac{\partial q_{0}}{\partial w_{0}}}{\frac{\partial q_{0}}{\partial w_{0}} - \frac{\partial q_{1}}{\partial w_{0}} \frac{\partial q_{0}}{\partial w_{0}}}}$$

Motivation 0000	Literature Review	Model 000000	Simultaneous 000000	Three-stage	Policy implications 0000●0	Simulations	Concluding remarks	
Perfec	t elastic de	mand						

	Simultaneous game	Three stage game
	t^*_{sim}	t _{3stage}
$egin{array}{l} heta &= 0, \ \gamma &= 0 \end{array}$	$\frac{\partial D}{\partial d_0}$	$\frac{\frac{\partial q_1}{\partial w_1} \left(\frac{\partial c_0}{\partial w_0} + d_0 \frac{\partial t_0}{\partial w_0} \right) - \frac{\partial q_0}{\partial w_0} \left(\frac{\partial c_1}{\partial w_1} + d_1 \frac{\partial t}{\partial w_1} \right)}{\frac{\partial q_0}{\partial w_0} \frac{\partial d_1}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial q_0}{\partial w_0}}$
$ heta > 0, \ \gamma = 0$	$\frac{\partial D}{\partial d_0} - \frac{\theta Q \frac{dq_0^*}{dt} \frac{\partial f(Q)}{\partial q_0}}{\frac{\partial d_0^*}{\partial t} + \frac{\partial d_1^*}{\partial t}}$	$\frac{\frac{\partial q_1}{\partial w_1} \left(\frac{\partial c_0}{\partial w_0} + d_0 \frac{\partial t}{\partial w_0} \right) - \frac{\partial q_0}{\partial w_0} \left(\frac{\partial c_1}{\partial w_1} + d_1 \frac{\partial t}{\partial w_1} \right)}{\frac{\partial q_0}{\partial w_0} \frac{\partial d_1}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial q_0}{\partial w_0}}$
$ heta = 0, \ \gamma > 0$	$\frac{\partial D}{\partial d_0} - \frac{\gamma \frac{\partial D}{\partial d_0} \frac{\partial d_0^*}{\partial t}}{\frac{\partial d_0^*}{\partial t} + \frac{\partial d_1^*}{\partial t}}$	$\frac{\frac{\partial q_1}{\partial w_1} \left(\frac{\partial c_0}{\partial w_0} + d_0 \frac{\partial t}{\partial w_0} + \gamma \frac{\partial D}{\partial d_0} \frac{\partial d_0}{\partial w_0} \right) - \frac{\partial q_0}{\partial w_0} \left(\frac{\partial c_1}{\partial w_1} + d_1 \frac{\partial t}{\partial w_1} \right)}{\frac{\partial q_0}{\partial w_0} \frac{\partial d_1}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial q_0}{\partial w_0}}$
$egin{array}{l} heta > 0, \ \gamma > 0 \end{array}$	$\frac{\partial D}{\partial d_0} - \frac{\gamma \frac{\partial D}{\partial d_0} \frac{\partial d_0^*}{\partial t} + \theta Q \frac{dq_0^*}{dt} \frac{\partial f(Q)}{\partial q_0}}{\frac{\partial d_0^*}{\partial t} + \frac{\partial d_1^*}{\partial t}}$	$\frac{\frac{\partial q_1}{\partial w_1} \left(\frac{\partial c_0}{\partial w_0} + d_0 \frac{\partial t}{\partial w_0} + \gamma \frac{\partial D}{\partial d_0} \frac{\partial d_0}{\partial w_0}\right) - \frac{\partial q_0}{\partial w_0} \left(\frac{\partial c_1}{\partial w_1} + d_1 \frac{\partial t}{\partial w_1}\right)}{\frac{\partial q_0}{\partial w_0} \frac{\partial d_1}{\partial w_1} - \frac{\partial q_1}{\partial w_1} \frac{\partial d_0}{\partial w_0}}\right)}$

Motivation 0000	Literature Review	Model 000000	Simultaneous 000000	Three-stage 0000000	Policy implications 00000●	Simulations	Concluding remarks
Perfec	t inelastic o	demand	l				

- When $\eta_0 \rightarrow 0$ and $\eta_1 \rightarrow 0$, the marginal damage will be always greater than the optimal emission tax.
- Simultaneous game, $t_{sim}^* \to -\infty$, independently of the CSR motivations of the firms, which in practice means no taxes ($t_{sim}^* = 0$) or even a subsidy.
- Three-stage game $t^*_{3stage} \rightarrow 0$.

Motivation	Literature Review	Model 000000	Simultaneous 000000	Three-stage	Policy implications	Simulations ●0000	Concluding remarks
Nume	rical exercis	se					

Using standard function specifications (Petrakis & Xepapadeas, 2003 or Fukuda & Ouchida, 2020):

•
$$Q = q_0 + q_1$$
, $f(Q) = a - Q$, $a > 0$.

•
$$c(q_i, w_i) = cq_i + w^2/2$$
.

•
$$d_i(q_i, w_i) = q_i - w_i$$
.

•
$$D(q_i, w_i) = d_i(q_i, w_i)^2/2 = (q_i - w_i)^2/2$$

Aggregated equilibrium levels for specific CSR motivations for the simultaneous game

Simulations

	PM	CF	EF	CEF
	$(heta=0,\gamma=0)$	$(heta=1,\gamma=0)$	$(heta=0,\gamma=1)$	$(heta = 1, \gamma = 1)$
t*	$\frac{7(a-c)}{43}$	$\frac{a-c}{4}$	$\frac{6(a-c)}{59}$	$\frac{2(a-c)}{11}$
Q^*	$\frac{24(a-c)}{43}$	$\frac{3(a-c)}{4}$	$\frac{32(a-c)}{59}$	$\frac{8(a-c)}{11}$
W^*	$\frac{14(a-c)}{43}$	$\frac{a-c}{2}$	$\frac{22(a-c)}{59}$	$\frac{6(a-c)}{11}$
D^*	$\frac{50(a-c)^2}{1849}$	$\frac{(a-c)^2}{32}$	$\frac{50(a-c)^2}{3481}$	$\frac{2(a-c)^2}{121}$
SW*	$\frac{15(a-c)^2}{43}$	$\frac{3(a-c)^2}{8}$	$\frac{20(a-c)^2}{59}$	$\frac{4(a-c)^2}{11}$

These are the results of a profit-maximizing firm with PM=profit maximizing, CF=Consumer friendly, EF=environmentally friendly, CEF=consumer-environmentally friendly.

Aggregated equilibrium levels for specific CSR motivations for the three-stage game

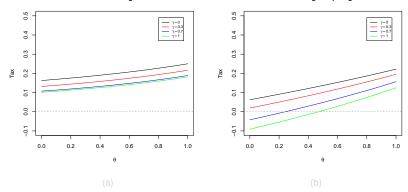
Simulations

	PM	CF	EF	CEF
	$(heta=0,\gamma=0)$	$(heta=1,\gamma=0)$	$(heta=0,\gamma=1)$	$(heta = 1, \gamma = 1)$
<i>t</i> *	<u>a-c</u> 16	$\frac{2(a-c)}{9}$	$-\frac{(a-c)}{11}$	$\frac{a-c}{8}$
Q^*	$\frac{5(a-c)}{8}$	$\frac{7(a-c)}{9}$	$\frac{13(a-c)}{22}$	$\frac{3(a-c)}{4}$
W^*	$\frac{a-c}{4}$	$\frac{5(a-c)}{9}$	$\frac{2(a-c)}{11}$	$\frac{a-c}{2}$
D^*	$\frac{9(a-c)^2}{128}$	$\frac{2(a-c)^2}{81}$	$\frac{81(a-c)^2}{968}$	$\frac{(a-c)^2}{32}$
SW*	$\frac{11(a-c)^2}{32}$	$\frac{260(a-c)^2}{729}$	$\frac{1313(a-c)^2}{4356}$	$\frac{67(a-c)^2}{200}$

These are the results of a profit-maximizing firm with PM=profit maximizing, CF=Consumer friendly, EF=environmentally friendly, CEF=consumer-environmentally friendly.

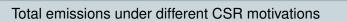
Optimal Emission Taxes for different CSR motivations

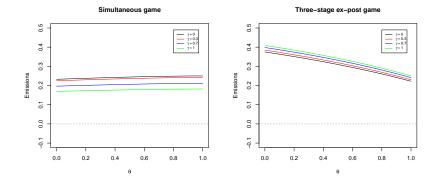
Simultaneous game



Three-stage ex-post game

Simulations





Simulations

Motivation 0000	Literature Review	Model 000000	Simultaneous	Three-stage 0000000	Policy implications	Simulations	Concluding remarks ●O
Conclu	uding rema	rks					

- We found different optimal, welfare enhancing, taxation rules when considering different CSR motivations.
- Using two different settings to model the Cournot duopoly, we found the same behavior in terms of taxation. However, in terms of emissions and environmental damage, the results are mixed.
- Based on the results of the three-stage game, we found that the best motivations for improving the state of the environment are consumer-friendly behavior and not environmentally-friendly firm.
- Our findings are relevant for environmental regulation, as they imply that behavioral biases, caused in this case by non-profit motives, must be considered when designing optimal emission taxes. A potential way to implement this policy could be through reporting and certification of CSR practices. This provides an avenue for future research on the subject.

Motivation 0000	Literature Review	Model 000000	Simultaneous 000000	Three-stage 0000000	Policy implications	Simulations 00000	Concluding remarks ○●
Next s	teps						

- Can CSR increase international trade?
- Special Issue on Environmental Economics and Economic Dynamics.